

# QGNPS-X-250B and QGNPS-Z-250B

## High-load 250 $\mu$ m piezo stage with capacitive sensor

Queensgate's nanopositioning stage (NPS) series are designed to provide optimal performance in the most demanding high-speed and high-precision applications.

The high-load lever amplified version is available calibrated in either the X (horizontal) or Z (vertical) orientation for the best performance in the customer's system.

Flexure-guided motion minimizes rotational errors and direct metrology of the moving platform with low-noise capacitive sensors ensures the highest precision of positioning.

User selectable calibration parameters provide optimal tuning for fast step-and-settle with different payloads (up to 6 kg as standard).



### Key Features

- 250  $\mu$ m travel with sub-nanometer resolution.
- Typically 0.005% hysteresis and 0.004% linearity error.
- Load capacity up to 6 kg.
- Flexure guided with lever amplification.
- Calibration for optimal performance in horizontal or vertical orientation.
- Direct moving platform measurement with capacitive sensors.

### Typical Applications

- Optical nosepiece positioning
- White light surface metrology
- Semiconductor inspection
- Precision manufacturing

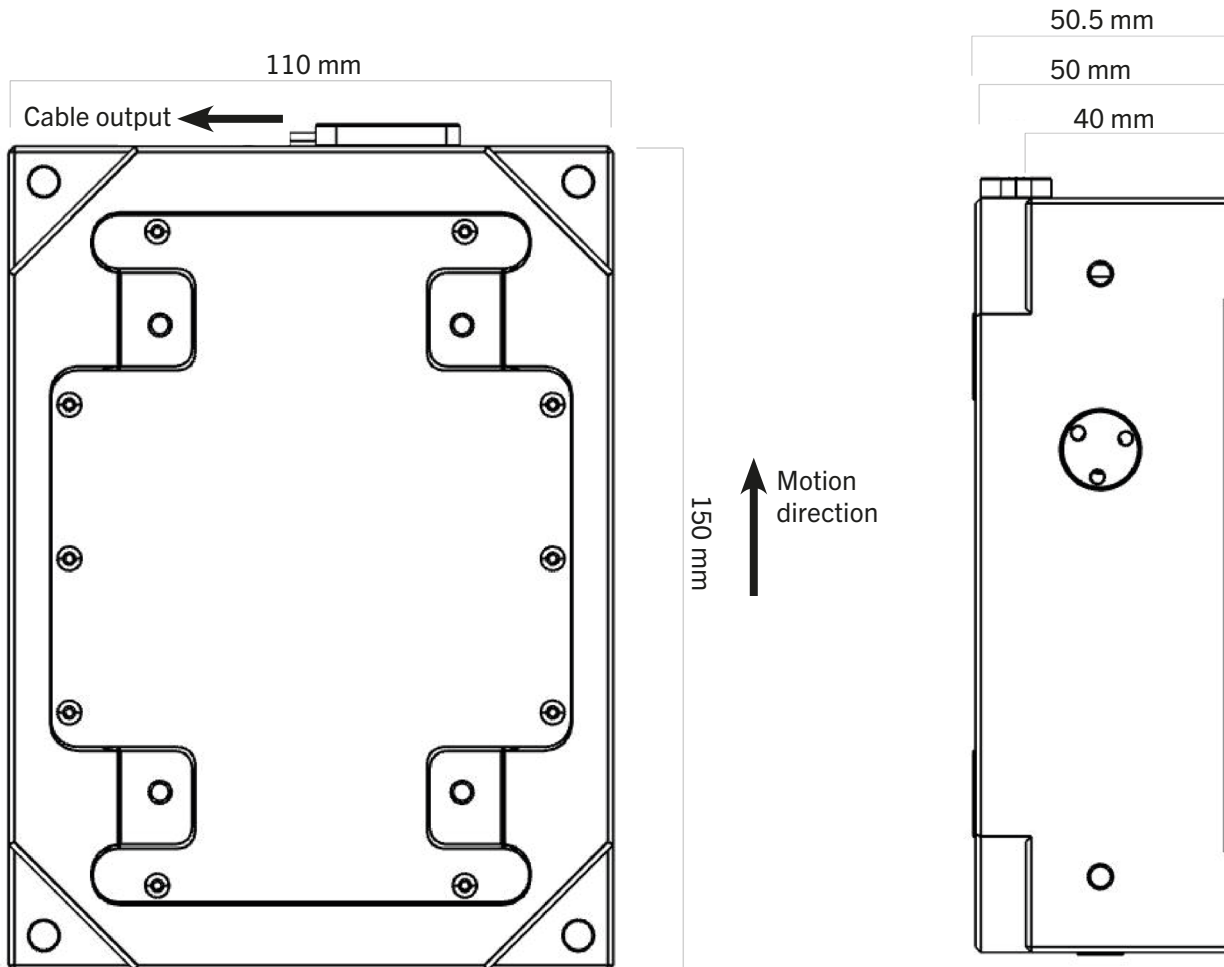
## Specifications

Parameter	Value			Units	Comments
Static physical					
Material	Aluminum (nickel plated)				
Size	150 x 110 x 50			mm	
Stage mass	2.0			kg	Excluding cable
Cable length	2			m	
*Open-loop range	310			μm	[Typical]
*Closed-loop range	250			μm	
Static stiffness	1.9			N·μm-1	
Resonant frequency	0 g load:	X: 325	Z: 315	Hz	[Typical]
	1 kg load:	X: 195	Z: 195		
	2 kg load:	X: 155	Z: 120		
	6 kg load:	X: 100	Z: 85		
Maximum load	6			kg	Note 1
Dynamic physical (typical values)					
	Fast (1 kg)	Medium (2 kg)	Slow (6 kg)		Note 2
*Settle time – 2 μm step	9	11	18	ms	Note 3
Settle time – 100 μm step	18	18	33		
*Position noise (1 σ)	0.6	0.6	0.6	nm <sub>rms</sub>	Note 4
Error terms					
	Typical		Maximum		
*Hysteresis (peak to peak)	0.005		0.02	%	Note 5
*Linearity Error (peak)	0.004		0.01		
Rotational error - roll	1			μradians	Note 6
Rotational error - pitch	1				
Rotational error - yaw	4				

**Preliminary specifications. Subject to change without notification.**

- Notes:
- \* These parameters are measured and supplied with each mechanism.
  - 1. Depends on load mass geometry and center of mass/gravity.
  - 2. For dynamic operation the servo-loop parameters are preset for different performances; the parameters are user settable via software control. Fast means the fastest the stage can stably move with less than 1 kg load. Medium means the maximum stable speed for loads up to 2 kg. Slow means the speed at which the servo loop is stable for all masses up to the maximum allowed mass (6 kg).
  - 3. This is the 2 % settle time. It is a function of the servo loop parameters which are user controllable.
  - 4. The actual position noise of the stage as measure with a laser interferometer.
  - 5. Percent error over the closed-loop range.
  - 6. Angular motion over the full closed-loop range of the stage.

## Dimensions\*



\*Please refer to the [Installation Drawing](#) for complete dimensions.

## Ordering Information

Part Number	Description
QGNPS-X-250B-D1	NPS-X-250B Piezo Stage System with a NPC-D-6110 (Horizontal Cal., 250 $\mu$ m).
QGNPS-Z-250B-D1	NPS-Z-250B Piezo Stage System with a NPC-D-6110 (Vertical Cal., 250 $\mu$ m)

### UNITED KINGDOM

Prior Scientific Instruments Ltd.  
Units 3-4 Fielding Industrial Estate  
Wilbraham Road, Fulbourn  
Cambridge, CB21 5ET  
United Kingdom  
Email: [inquiries@prior.com](mailto:inquiries@prior.com)  
Phone: +44 (0)1223 881711

### U.S.A.

Prior Scientific, Inc.  
80 Reservoir Park Drive  
Rockland, MA. 02370  
U.S.A.  
Email: [info@prior.com](mailto:info@prior.com)  
Phone: +1 781 878 8442

### GERMANY

Prior Scientific Instruments GmbH  
Maria-Pawlowna-Str. 4  
D-07743, Jena, Germany  
Email: [jena@prior.com](mailto:jena@prior.com)  
Phone: +49 (0)3641 242 010

### JAPAN

Kayabacho 3rd Nagaoka Bldg 10F,  
2-7-10, Nihonbashi Kayabacho, Chuo-Ku,  
Tokyo103-0025, Japan  
Email: [info-japan@prior.com](mailto:info-japan@prior.com)  
Phone: +81 (0)3 5652 8831

### CHINA

Prior Scientific Instruments (Suzhou) Ltd.  
Room 118, Meilihua Hemu Park  
No. 393 Suhong Middle Road, Suzhou Industrial Park  
Suzhou, 215000, China  
Email: [info-china@prior.com](mailto:info-china@prior.com)  
Phone: +86 (0)512 6617 5866



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