

# NanoScan NPC-D-6000 Series

**Closed Loop Digital Controllers** 

The NPC-D-6000 series are single and multi-channel digital nanopositioning controllers.

The NPC-D-6330 is capable of controlling up to 3 piezo driven actuators and 2 or 3 axis nanopositioning systems. The NPC-D-6110 is a single channel version delivering the same performance for single axis nanopositioning systems.

Designed to operate in closed loop with stages or actuators incorporating capacitance positioning sensors the controllers deliver low noise, low drift, high power and high resolution. Fast position update rates contribute to high speed positioning accuracy for dynamic applications that require high speed movement of the stage.

The NPC-D-6000 series controllers deliver repeatability of movement with improved precision and accuracy for

precise imaging and focusing at higher maximum speeds with fast step settle times. This can be particularly important for longer range stages or stages designed for high load bearing.

### **Key Features**

- Closed loop controller with open loop operating mode.
- Capacitance sensor measurement circuitry for precision closed loop operation.
- Digital signal processing with 24 bit data resolution. Fast
- 20µs control loop update.
- 4th order linearization algorithm for high positional accuracy.
- Supports Plug and Play NanoMechanisms. The calibration and dynamic settings are held in the stage EEPROM allowing controllers to be interchanged with minimal impact on performance.
- Two notch filters for tuning to meet specific application requirements, reducing noise and preventing stage ringing.





- Two notch filters for tuning to meet specific application requirements, reducing noise and preventing stage ringing.
- The low noise design allows stage position noise as low as a few tens of picometres. Delivering a stable system with repeatability of movement, precision and accuracy for precise imaging and focusing.
- Dynamic high-power output NanoMechanism drive with 20 bit resolution.
- Optimized acceleration/deceleration contribute to high speed positioning applications by reducing overshoot and settle time.
- Soft-start/stop technology protects loads and increases piezo life.



## Interfacing

- Analog command and position output +/-10 V or 0-10V
- Digital commands over USB or optional RS232C and Ethernet control interfaces.
- Easy to interface with OEM software using supplied DLL (Dynamic Link Library).
- Examples of software in C/C++, Python and LabVIEW<sup>®</sup> provided.
- User programmable Function Playback of custom programmed waveforms such as constant velocity profiles.
- User programmable TTL input/output triggers intregrated with function play back to interface with external devices.
- TTL In-position digital outputs can be used to interface with external devices
- Digital TTL quadrature or step and direction inputs/outputs allowing high speed control with a standard 2 wire motion controller interface, without the need for expensive high precision ADCsS/DACs.

### **Technical specification**

Parameter	Value	Units	Comments
Mechanical	'		
Size:	318 x 240 x 90	mm	Height includes feet.
NPC-D-6330			Not including protruding components at front and rear of controller.
NPC-D-6110	318 x 240 x 90	mm	Additional space required for rear connectors and cables.
Weight	2.6	kg	
Cooling	Fan forced air		Vents on rear and base
Electrical			
Power input	100 to 240 nominal	Vrms	Using external supply. Only use approved power supply
	47 to 63	Hz	-provides protective earth connection.
DC power input	± 24 ± 0.75@5A	V	Only use Queensgate approved power supply
DC power input connector	4 pin DIN Plus protective		Rear panel
	earth connection		
Connectivity			
USB	2.0 compliant		USB type B connector. Note: power not taken from USB port.
Ethernet	IEEE 802.3		RJ45 connector. Requires a Cat 5 male to male cable.
			MUST use shielded Ethernet cable.
Analogue input command	BNC		Per channel - front panel
Analogue Position Monitor	BNC		Per channel - front panel
output			
"TRIG" input, "TRIG" output,	25 pin D-type socket		
"IN-POS" output and			
Quadrature Interface			
Controller Synchronizing signals	9 pin D-type socket		Rear panel
Environmental - Operational	·		
Temperature	10 to 40	⁰C	
Relative Humidity	5 to 80	%RH	Non-condensing

### **Technical specification**

Parameter	Value	Units	Comments
Environmental - Storage and	Shipping		
Temperature	-20 to 70	⁰C	
Relative Humidity	0 to 95	%RH	Non-condensing
General			
Warm up time	40 (typ)	Min	
"ANA I/P" analogue input	-10 to +10	V	Connector BNC – Single ended MAXIMUM input: ±10V
position command per channel			Input maybe cailbrated to 0-10V range if required
"ANA I/P" analogue input impedance (per channel)	> 50k	Ohms	
"POS MON" analogue output position monitor per channel	-10 to +10		Connector BNC – Single ended MAXIMUM input: ±10V Output maybe cailbrated to 0-10V range if required
Function Playback trigger inputs and outputs	TTL logiv levels	V	25 pin D-Type on rear panel.
	Logic "0" < 0.8	V	Inputs - input impedance 50 ohms, MAXIMUM input 5.5V
Stepped inputs and outputs in position output	Logic "1" 2.4 to 5		Outputs Load impedance: > 1k ohms. MINIMUM
NanoMechanism interfacing	– controller – per channel		
Connector	17W2 D type		Mixed signal connector
HV output swing	-30 to +150	V	Factory set (default)
	-20 to +120		Factory set (optional)
HV drive current	160	mA	Factory set (default)
HV amplifier bandwidth	>50	kHz	
HV amplifier intrinsic noise	0.3	mV	

### **Ordering information**

Product Ref	Description	
QGNPC-D-6330	NanoScan NPC-D-6330 Multi-Channel Closed Loop Controller	
QGNPC-D-6110	NanoScan NPC-D-6110 Single Channel Closed Loop Controller	

Owing to continuous development, we reserve the right to introduce improvements and modify specifications without prior notice.

#### UNITED KINGDOM

Prior Scientific Instruments Ltd. Units 3-4 Fielding Industrial Estate Wilbraham Road, Fulbourn Cambridge, CB21 5ET United Kingdom Email: inquiries@prior.com Phone: +44 (0)1223 881711

#### U.S.A.

Prior Scientific, Inc. 80 Reservoir Park Drive Rockland, MA. 02370 U.S.A. Email: info@prior.com Phone: +1 781.878.8442

#### GERMANY

Prior Scientific Instruments GmbH Maria-Pawlowna-Str. 4 D-07743, Jena, Germany Email: jena@prior.com Phone: +49 (0) 3641 24 20 10

#### JAPAN

Kayabacho 3rd Nagaoka Bldg 10F, 2-7-10, Nihonbashi Kayabacho, Chuo-Ku, Tokyo103-0025, Japan Email: info-japan@prior.com Phone: 03-5652-8831

#### CHINA

Prior Scientific Instruments (Suzhou) Ltd. Room 1812, Honghai Building, 72 Xingdu Street, Suzhou Industrial Park, Suzhou, 215000 China Email: info-china@prior.com Phone: +86 (0)512 6617 5866



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